Mass General Brigham Mass Eye and Ear

Abstract

Background/Objective: In computer vision (CV), detection tasks involve classifying and bounding a structure of interest. We aimed to develop a proofof-concept model for automated anatomy and instrument detection during transcanal endoscopic ear surgery (TEES).

Methods: We developed a detection model to identify instruments and middle ear anatomy during TEES for cases of otosclerosis and ossiculoplasty. An internal model was trained and tested on institutional TEES images. This internal model was then externally validated on an images extracted from TEES videos obtained from YouTube. Images in which middle ear anatomy or instruments were not visualized were excluded. Detections were evaluated using recall and intersection over union (IoU).

Results: On the internal dataset, the model achieved an overall recall/IoU of 73%/65% compared to 65%/67% on the external validation dataset. On both the datasets, instrument detection was most precise and accurate. Detection of anatomic structures was generally more accurate for structures with clear, well-defined borders.

Conclusions: A CV approach for instrument and anatomy tracking during TEES is feasible and may contribute to development of augmented reality-based endoscopic ear video systems.

Methods

- 1,045 images from 5 institutional TEES recordings used to train and test an internal model using five-fold cross validation.
- Internal model was then validated on 100 external images from 5 TEES YouTube videos.
- All images manually annotated to create ground-truth annotations. Structures of interest included the chorda tympani, incus, instruments, promontory, and stapedial tendon.
- Open-source CV toolkit, Detectron2, utilized to train and test models¹.
- Model performance determined by accuracy of classification (recall) and precision of detection (IoU) (Figure 1).



Figure 1. IoU, a precision metric, represents the ratio of the area of overlap to the area of union between the ground truth and predicted annotations. Recall represents the true positivity rate.

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Computer Vision Approach for Instrument and Anatomy **Detection during Transcanal Endoscopic Ear Surgery**

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True Positives

True Positives + False Negatives

Results: instrument/anatomy detection during TEES is feasible

• Structure-specific detection performance on both both internal and external datasets is reported in Table 1.

| Structure | Five-Fold Validation | | External Validation | |
|-----------|----------------------|-----------------|---------------------|-----|
| | Recall \pm std | $IoU \pm std$ | Recall | loU |
| inst | 94 <u>+</u> 4% | 84 <u>+</u> 3% | 91% | 82% |
| in | 89 <u>+</u> 12% | 67 <u>+</u> 10% | 52% | 74% |
| ct | 81 <u>+</u> 11% | 69 <u>+</u> 4% | 75% | 68% |
| pr | 69 <u>+</u> 36% | 54 <u>+</u> 11% | 22% | 41% |
| st | 30 <u>+</u> 26 % | 51 <u>+</u> 35% | 10 % | 70% |

Table 1. Structure specific performance on both internal and external testing. ct – chorda tympani, in – incus, inst – instrument, pr – promontory, st – stapedial tendon

- Examples of model predictions on both external and internal images are displayed in Figure 2-3. Percentages represent model confidence of prediction.
- A demonstration of live anatomic and instrument tracking can be accessed at the QR code below.





SCAN HERE FOR A LIVE DEMO



References







Figure 3. Model predictions on external YouTube TEES images. A) Left ear, high-quality image where model performs well. B) Left ear, poorer quality image where model performance falls; note missed detections of the chorda tympani, incus, and stapedial tendon. ct – chorda tympani, in – incus, inst – instrument, pr – promontory, st – stapedial tendon. Images accessed publicly under the Creative Commons License. Credit: The image in panel A is obtained from a video uploaded by Dr. João Flávio Nogueira. The image in panel B is obtained from a video uploaded by Dr. Gouda Ramesh.

- field
- Limitations:
 - biased towards high-quality image data.
- Future directions:
 - included and in video quality)

 - dimensional video data

- instruments during TEES.
- and robotic-assisted surgical platforms.

1. <u>https://github.com/facebookresearch/detectron2</u>

2. Kozin ED, Lee DJ, Pollak N. Getting Started with Endoscopic Ear Surgery. Otolaryngol Clin North Am. 2021;54(1):45-57. doi:10.1016/j.otc.2020.09.009 3. Mahadevkar S V., Khemani B, Patil S, et al. A Review on Machine Learning Styles in Computer Vision—Techniques and Future Directions. IEEE Access. 2022;10:107293-107329. doi:10.1109/ACCESS.2022.3209825 4. You E, Lin V, Mijovic T, Eskander A, Crowson MG. Artificial Intelligence Applications in Otology: A State of the Art Review. Otolaryngol Head Neck Surg. 2020;163(6):1123-1133. doi:10.1177/0194599820931804 5. Ward TM, Mascagni P, Ban Y, et al. Computer vision in surgery. Surgery. 2021;169(5):1253-1256. doi:10.1016/j.surg.2020.10.039



Discussion

Excellent instrument detection given unique appearance in the surgical

• Anatomic structures with distinct borders (ie incus, chorda) tended to have better detection than those with indistinct boundaries (ie promontory)

Model trained on high-definition endoscopic video data and is thus

Model trained with video data from only ossiculoplasty or stapes surgery. Thus, performance cannot be generalized to all TEES cases.

Retraining with more heterogenous data (both in types of surgeries

Development of companion model for depth prediction from two-

Conclusions

We developed a CV detection model for tracking anatomy and

This approach could be used for development of novel training, navigation