

# A dynamic scheduling method for autonomous maintenance of human iPS cells without human intervention.



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## 1. Introduction

### Background

- There is not flexible autonomous maintenance system for multiple human iPS cell lines.

### Purpose

- We aim to make a scheduler for the autonomous maintenance and a simulator for its evaluation.

### Keywords

- Multiple maintenance culture
- Single machine scheduling
- Dynamic scheduling

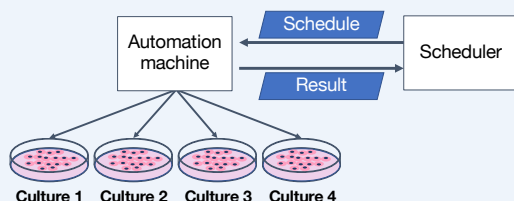


Figure 1 Visual abstract

## 2. Materials & Methods

### Problem settings

- You want to continue maintaining human iPS cells.
- Maintenance are composed of several operations in a sequential manner.
- The next operation and its optimal time are determined according to the current operation and cell information (density and quality).
- The scheduler must determine when to perform each operation.
- Each type of operation has its priority.

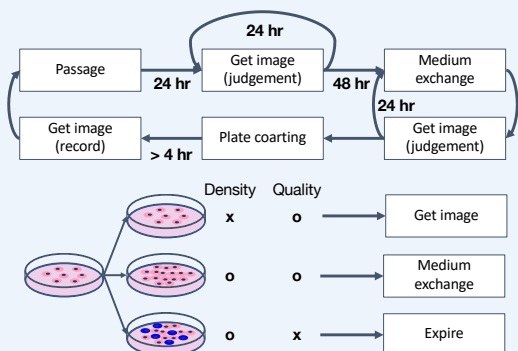


Figure 2 Culture state transition

### Scheduler

- The objective function ( $S$ ) is to minimise the total weighted earliness and tardiness for the optimal time ( $t$ ) of each operation.

$$S = \sum_i W_i (|t_i - t_i^*|)$$

- $W_i$ : Weighted penalty function for  $i$ -th operation

- We use simulated-annealing algorithm for scheduling

- To reduce variance due to stochasticity, scheduler runs parallel multi-threaded computations

--- Optimal time  
 — Penalty  
 ■ Just on time

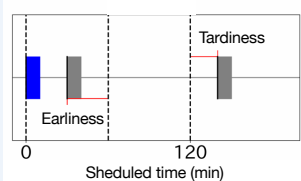


Figure 3 Objective function

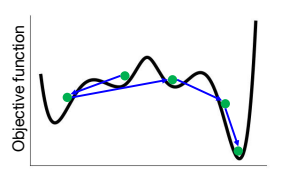


Figure 4 Simulated-annealing algorithm

## 3. Results

### Simulator

- The simulator simulates cell growth, changes in cell quality, execution of the entered schedule and returns results.
- The following conditions are assumed in this experiment.
  - Operation  $a$  failure probability  $F(a)$  is set constant ( $F(a) = 0$ ).
  - Each cell line has an independent growth curve.
  - Each cell line has a different initial state.
  - Cell quality of cell line  $i$  at timepoints  $t$   $Q(i, t)$  is set constant ( $Q(i, t) = 1$ ).
- The simulation ends when 500 operations have been performed.

## 3. Results

### Simulation experiment

- The scheduler could continuously find schedules without error (overlapping schedule).



- The scheduler completed the simulation equivalent to 39.5 days in approximately 9 min.

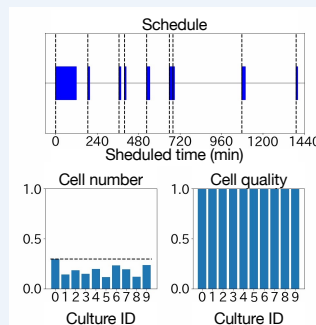


Figure 5 Simulation output

- For each Cell line, eight to nine passaging operations were performed.

- The average time lag of execution of each operation was 4.28 min (blue dotted line in Fig.7).

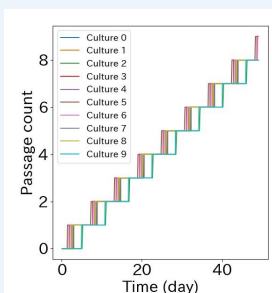


Figure 6 Total passage count

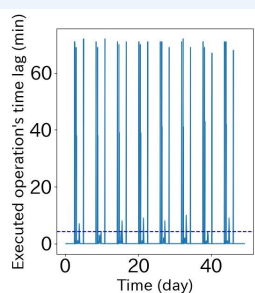


Figure 7 All executed operation's time lag

## 4. Discussion

### Conclusions

- Establish the scheduler for autonomous maintenance of human iPS cells
- We conducted experiments with the simulator and confirmed that the scheduler works properly.

### Future plan

- Simulation with real-world settings
  - Consumption of reagents
  - Operation failure (delay)
  - Observation error
- Real-world autonomous experiments

## 5. Acknowledgements

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